

## Multi-system Multi-function

K801 supports multi-system, multi-frequency signal tracking. Contains high-precision GNSS measurement engine. The navigation engine supports high-performance RTK positioning.

## Low latency Mini size

Module surface mount design, the size is 16mm×12mm×2.2mm, low latency, and power consumption is 0.15W.

## Anti-interference

It is built-in narrowband and continuous wave suppression algorithm engine. It can effectively deal with satellite signal interference environments, providing stable continuous and reliable high-precision position information.

# K801

## HIGH-PRECISION POSITIONING GNSS MODULE



16mm×12mm×2.2mm



IoT



ID



UAV



Robot

The K801 module is a multi-system, multi-frequency, mini-size, high-precision positioning OEM module independently developed by QinNav Technology Ltd. It supports signal positioning, including GPS, BDS-2, BDS-3, GLONASS, Galileo, SBAS and QZSS, it is mainly used for Mower, UAV and handheld devices with size, weight, and power requirements.

- Size: 16mm×12mm, Multi-System, multi-frequency, surface mount design
- Signal Tracking: BDS、GPS、GLONASS、Galileo、QZSS\*、SBAS\*
- Low latency
- Power: 0.15W

\*Due to factors such as product iteration or technical updates, the product information provided in this document includes but is not limited to product names, parameters, and specifications that may change from time to time without prior notice. Please refer to the latest version of the specification file or consult with the staff.

**SinoGNSS / QinNav**  
By ComNav Technology Ltd.

QinNav Technology, LTD.

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# K801 HIGH-PRECISION POSITIONING GNSS MODULE

## Signal Tracking

BDS	B1I, B2a
GPS	L1C/A, L5
GLO	G1
GAL	E1, E5a
QZSS*	L1C/A, L5
SBAS*	L1C/A

## Time to First Fix

Cold Start	< 24s
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## Accuracy

Timing Accuracy (RMS)	5ns
SPP Accuracy	$H \leq 1.5m, V \leq 3m$ ( $1\sigma$ , PDOP $\leq 4$ )
Speed Accuracy	$\leq 0.02m/s$ (PDOP $\leq 4$ )
RTK Initialization Time	< 15s (D<10km)
RTK Initialization Reliability	> 99.9 %
RTK Accuracy	H: $\pm (10 + 10^{-6} \times D)$ mm V: $\pm (15 + 10^{-6} \times D)$ mm D-Baseline length (Unit: mm)

## IMU\*

Optional

### Gyroscope\*

Range	$\pm 250^\circ/s$
Zero bias stability	3.5°/h

### Accelerometer\*

Range	$\pm 8g$
Zero bias stability	25 $\mu g$ (x, y) 100 $\mu g$ (z)

## Data Rates

Measurement & Position	5Hz (Optional)
RTK	5Hz (Optional)
IMU*	50Hz (Optional)

## Electrical

Voltage	+ 3.3V~+3.45V DC
Power Consumption	0.15W

## Environmental

Operating Temperature	-40°C ~ +85°C
Storage Temperature	-40°C ~ +85°C

## Data Formats

NMEA-0183	GPGLL, GPGSV, GPRMC, GPVTG, GPZDA, GPRMC, GPZDA, GPRMC etc.
RTCM3.X	1005, 1019, 1020, 1042, 1044, 1046 MSM4: 1074, 1084, 1094, 1114, 1124 MSM7: 1077, 1087, 1097, 1117, 1127

## Antenna Interface

Impedance Matching	50 $\Omega$
Antenna Voltage	External: +3.3V~+5V @ (0-100) mA
Antenna Gain	15dB~35dB

## Hardware Interface

UARTx2, PPSx1, I<sup>2</sup>Cx2, USBx1

## Physical

Size	16mm×12mm×2.2mm
Weight	1.0g
Package	LGA 24Pin

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